



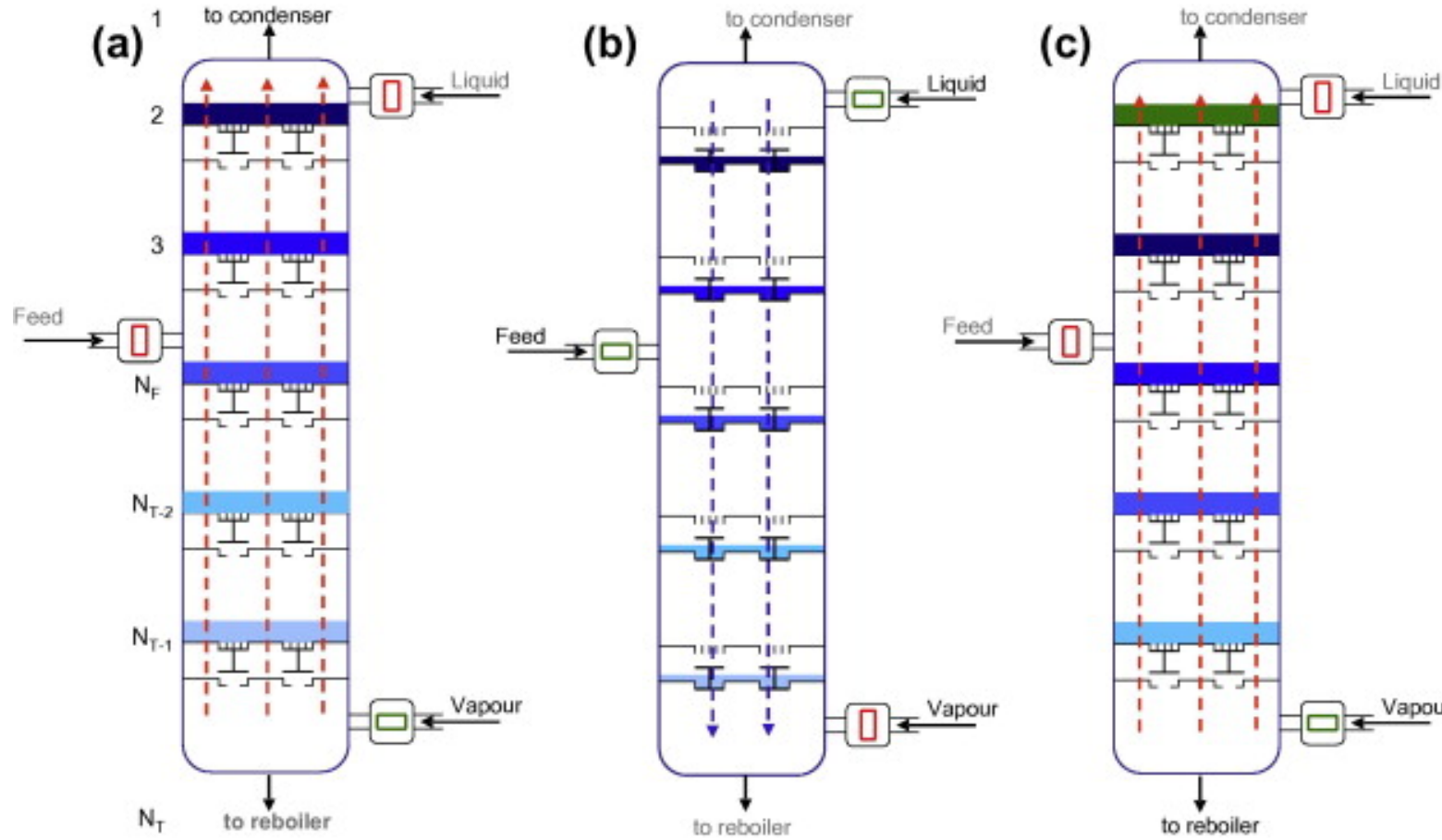
INTRODUCTION

Context. Cyclic distillation separates vapor contacting from liquid transport. Vapor flows while liquid is retained during the VFP; liquid is displaced downward during the LFP. Under the ideal displacement model, this sequence reduces interstage liquid remixing and can lower the cycle-average vapor requirement.^[1–5]

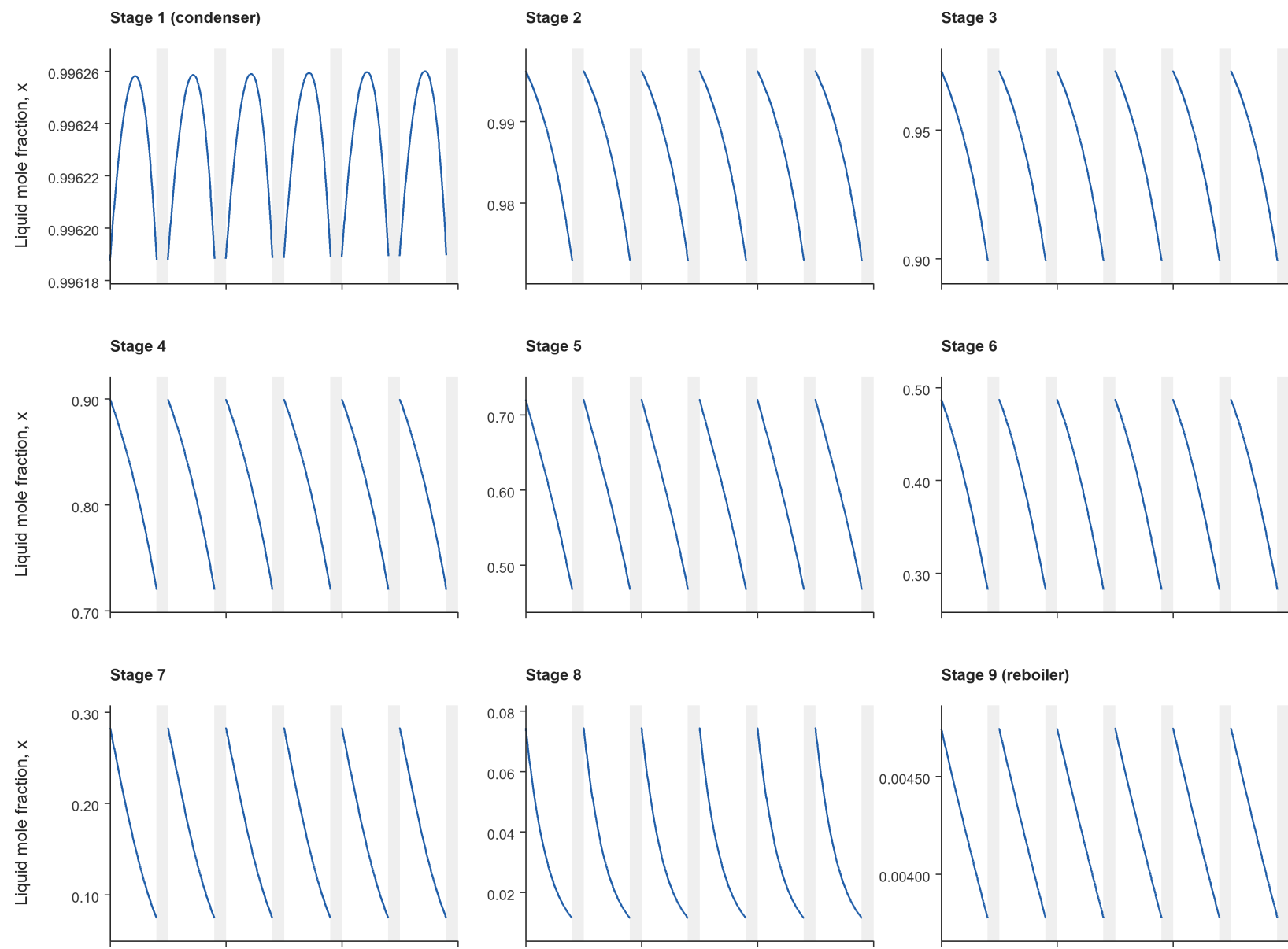
Gap. The nominal operating state is a repeatable VFP–LFP trajectory, not a stationary composition profile. Vapor requirement characterizes separation performance, but it does not show whether this periodic orbit attracts disturbances or how fast the column returns to it.

Aim. We formulate one complete cycle as a Poincaré map. Its Floquet multipliers classify local orbital stability, and its dominant eigenvector and decay rate identify the spatial structure and time scale of slow recovery.^[6,7]

CASE 1 | PERIODIC OPERATION



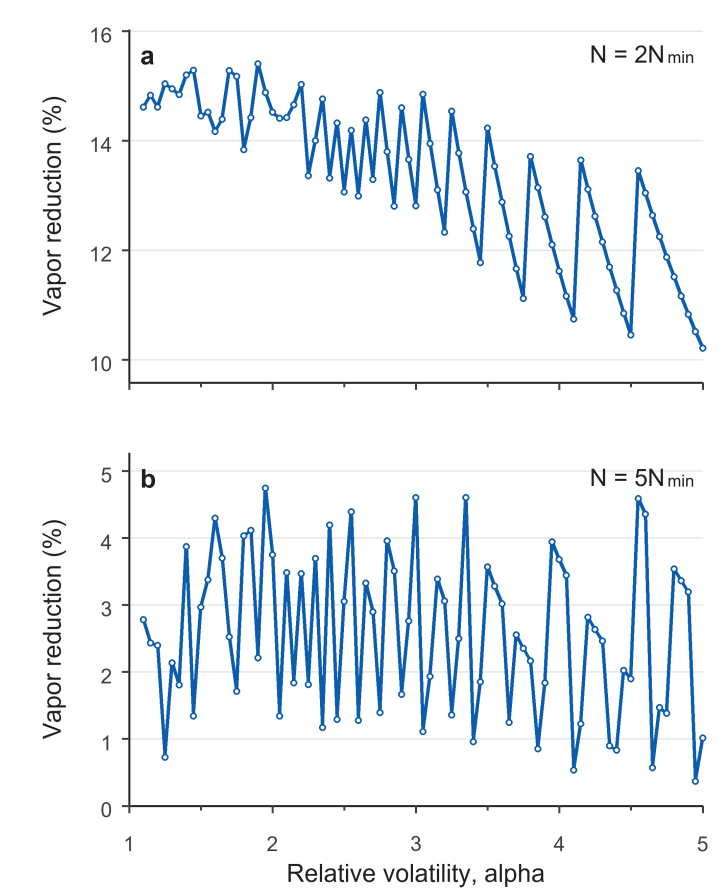
Two-period sequence. Vapor contacts the retained liquid during the VFP; the LFP then displaces liquid downward and withdraws products. **Benchmark:** $N = 9$, $n_f = 5$, $\alpha = 3.5$, $t_V/t_L = 12/3$ s. At equal average vapor input, cyclic operation gives $(x_D, x_B) = (0.9962, 0.0047)$ versus $(0.9616, 0.0384)$ continuously.



Eulerian view. Sampling the fixed tray compositions at the same phase of each cycle converts the periodic trajectory into a sequence of state vectors.

CASE 2 | RELATIVE VOLATILITY

This case asks whether the lower vapor requirement of cyclic operation persists as the separation difficulty changes. The feed is fixed at $F = 0.0250$ kmol/s with $x_F = 0.5$, and both columns must meet the same targets, $x_D = 0.995$ and $x_B = 0.005$. Only the relative volatility is scanned.

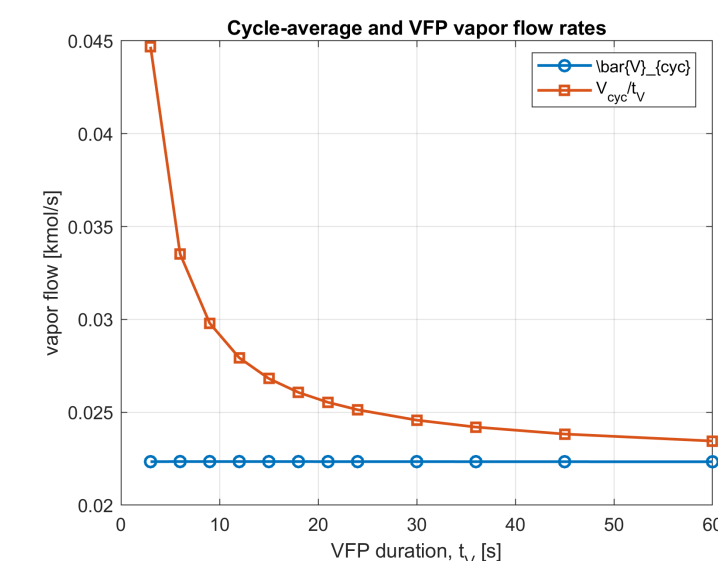


$\alpha = 1.10\text{--}5.00$
79 points per scan
 $N = \lceil 2N_{\min} \rceil$: **10.20–15.40%**
 $N = \lceil 5N_{\min} \rceil$: **0.37–4.74%**
Base case:
14.23% reduction
At fixed $\alpha = 3.5$ and $n_f = 10$, increasing $N = 15 \rightarrow 19$ reduces the advantage from **27.64% to 9.65%**.

$\eta_V = 100(1 - \bar{V}_{\text{cyc}}/\bar{V}_{\text{conv}})$ is the relative reduction in calculated cycle-average molar vapor requirement, not a thermodynamic efficiency.

CASE 3 | VFP/LFP DURATION

This case isolates cycle timing from the volatility and stage-selection effects in Case 2. The base separation is fixed at $\alpha = 3.5$, $N = 17$, $n_f = 10$, $F = 0.0250$ kmol/s, $x_F = 0.5$, $x_D = 0.995$, and $x_B = 0.005$. Because the ideal LFP is an algebraic displacement event, $t_L = 3$ s is fixed while t_V is varied.



$t_V = 3\text{--}60$ s
 $\bar{V}_{\text{cyc}} \approx 0.02235$ kmol/s and changes by $< 0.05\%$.
Per-cycle vapor amount:
0.13405 $\rightarrow$ 1.40720 kmol/cycle.
Instantaneous VFP flow:
0.044682 $\rightarrow$ 0.023453 kmol/s.

Longer VFPs spread the required vapor over more contact time: the average requirement stays almost unchanged while instantaneous loading falls. Actual flooding, entrainment, weeping, and drainage limits require tray geometry and fluid-property data and are not predicted here.

CASES 2–3 | DESIGN READING

Decision	Quantitative result	Design meaning
Stage count	$N = \lceil 2N_{\min} \rceil$: 10.20–15.40% reduction. $N = \lceil 5N_{\min} \rceil$: 0.37–4.74% .	The finite-stage vapor advantage decreases as the cyclic column approaches its high-stage limit.
Cycle timing	$t_V = 3\text{--}60$ s changes $\bar{V}_{\text{cyc}}$ by $< 0.05\%$, but lowers instantaneous VFP flow from 0.04468 to 0.02345 kmol/s.	Cycle duration redistributes vapor within the imposed sequence rather than changing its average requirement.
Design and reporting	Optimize N and n_f for vapor screening; select t_V against allowable instantaneous loading. Report η_V , $\bar{V}_{\text{cyc}}$, stage-count basis, and VFP/LFP timing.	Stage count sets the vapor advantage; timing sets how vapor is delivered. The result is not a heat-duty or thermodynamic-efficiency prediction.
Model boundary	Ideal binary VLE, constant relative volatility, CMO, and prescribed liquid displacement.	Hydraulic feasibility still requires tray geometry, fluid properties, flooding, weeping, entrainment, and drainage data.

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POINCARÉ MAP & BASE CASE

Objective. Determine whether the optimized periodic orbit attracts composition perturbations, how rapidly it recovers, and where its slowest spatial mode is concentrated.

Sample the fixed-stage composition vector at the start of each VFP. One complete VFP–LFP sequence defines the return map

$$\mathbf{x}^{k+1} = \mathcal{P}(\mathbf{x}^k), \quad \mathbf{x}^* = \mathcal{P}(\mathbf{x}^*).$$

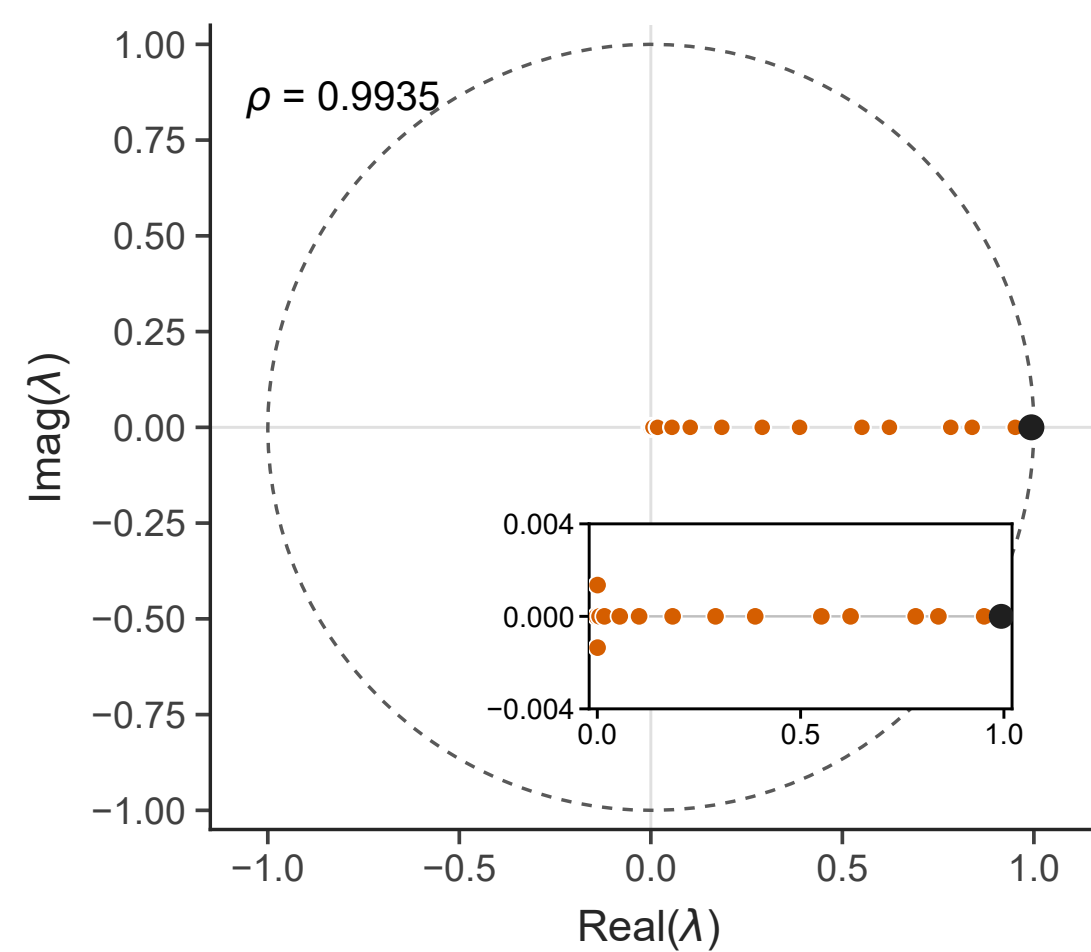
The variational VFP and differentiated LFP reset give

$$\mathbf{J}_x = \mathbf{H}_x \mathbf{R}_x \mathbf{S}_V(t_V) \mathbf{Z}_x, \quad \rho = \max_j |\lambda_j(\mathbf{J}_x)|.$$

Local orbital stability requires $\rho < 1$; $N_{1\%} = \ln(0.01)/\ln \rho$.^[6,7]

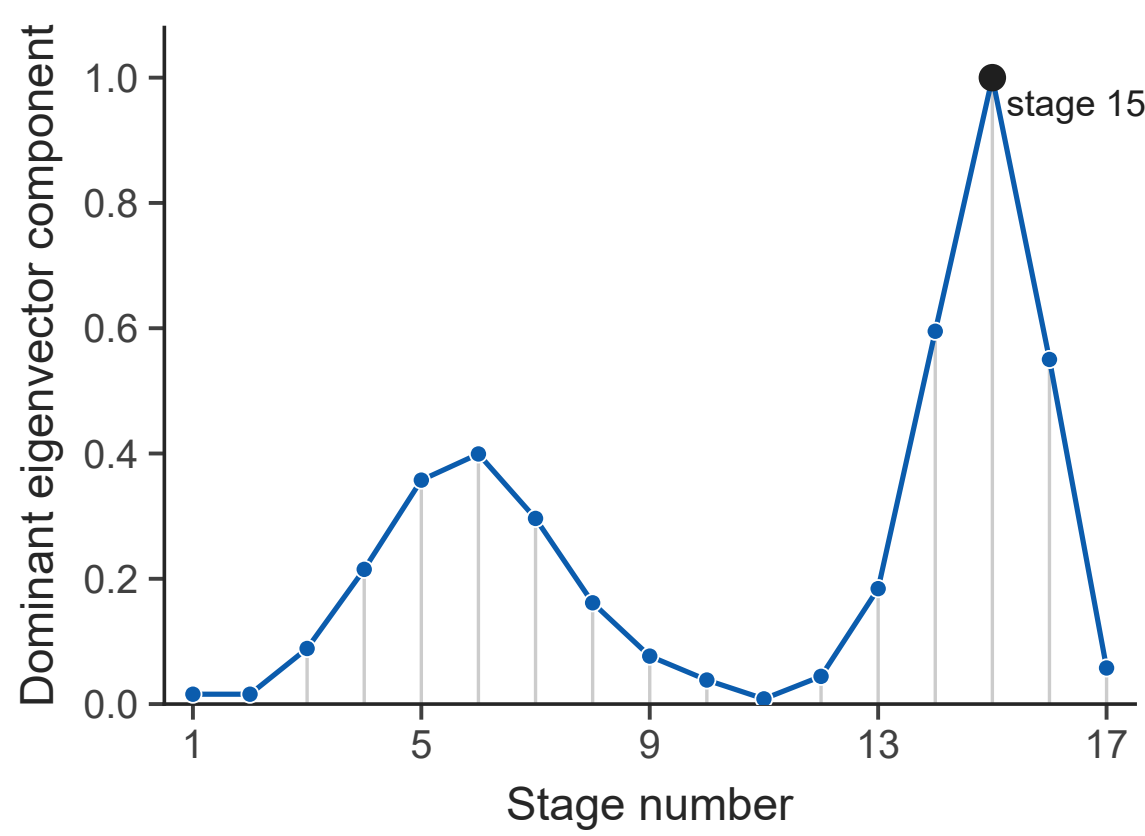
CASE 4 | BASE-CASE LOCAL STABILITY

A FLOQUET MULTIPLIERS



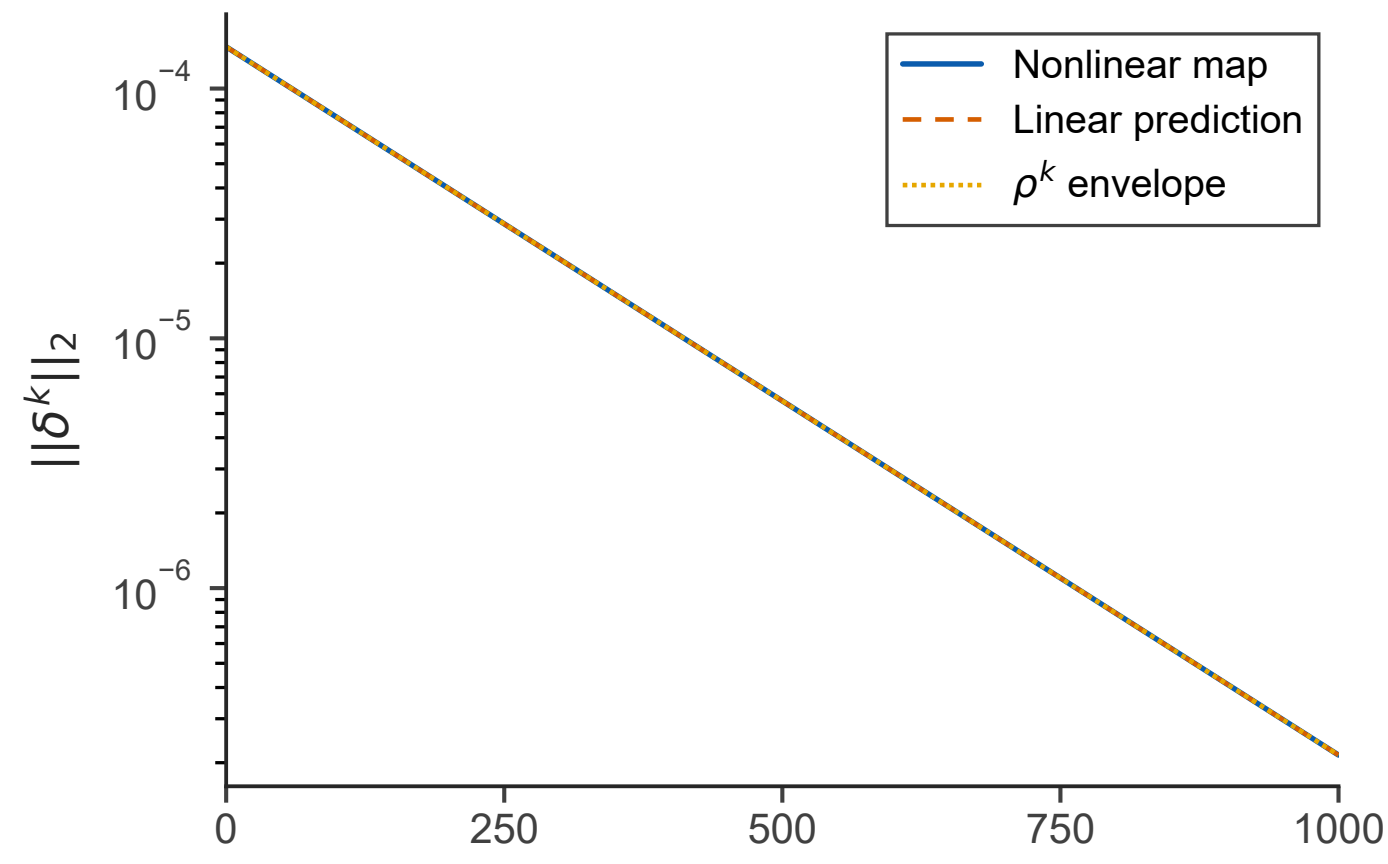
All multipliers lie inside the unit circle; $\rho = 0.993492$ implies local stability but weak attraction.

B DOMINANT SPATIAL MODE



The slow mode peaks at stage 15, with large neighboring contributions at stages 14 and 16.

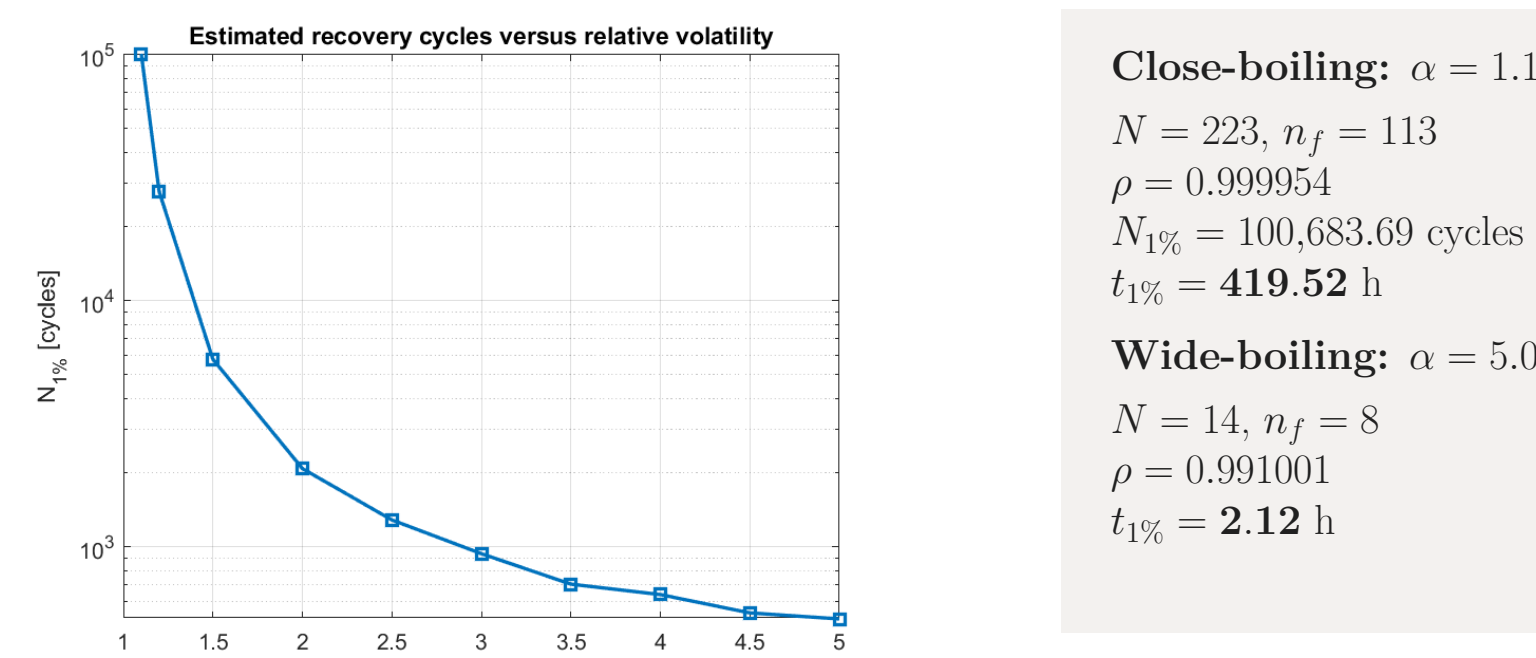
$$\rho = 0.993492 \mid N_{1\%} = 705.32 \text{ cycles} \mid t_{1\%} = 2.94 \text{ h}$$



For a dominant-mode perturbation, nonlinear recovery, the linear map, and the ρ^k reference decay nearly coincide.

CASE 5 | RELATIVE VOLATILITY AND STABILITY

Using the optimized stage number and feed location from Case 2, this case asks how separation difficulty changes the local attraction of the periodic orbit. The product specifications and cycle time remain fixed; the Poincaré map is recomputed for each α .



Close-boiling: $\alpha = 1.1$
 $N = 223$, $n_f = 113$
 $\rho = 0.999954$
 $N_{1\%} = 100.683.69$ cycles
 $t_{1\%} = 419.52$ h
Wide-boiling: $\alpha = 5.0$
 $N = 14$, $n_f = 8$
 $\rho = 0.991001$
 $t_{1\%} = 2.12$ h

TEN OPTIMIZED PERIODIC STATES

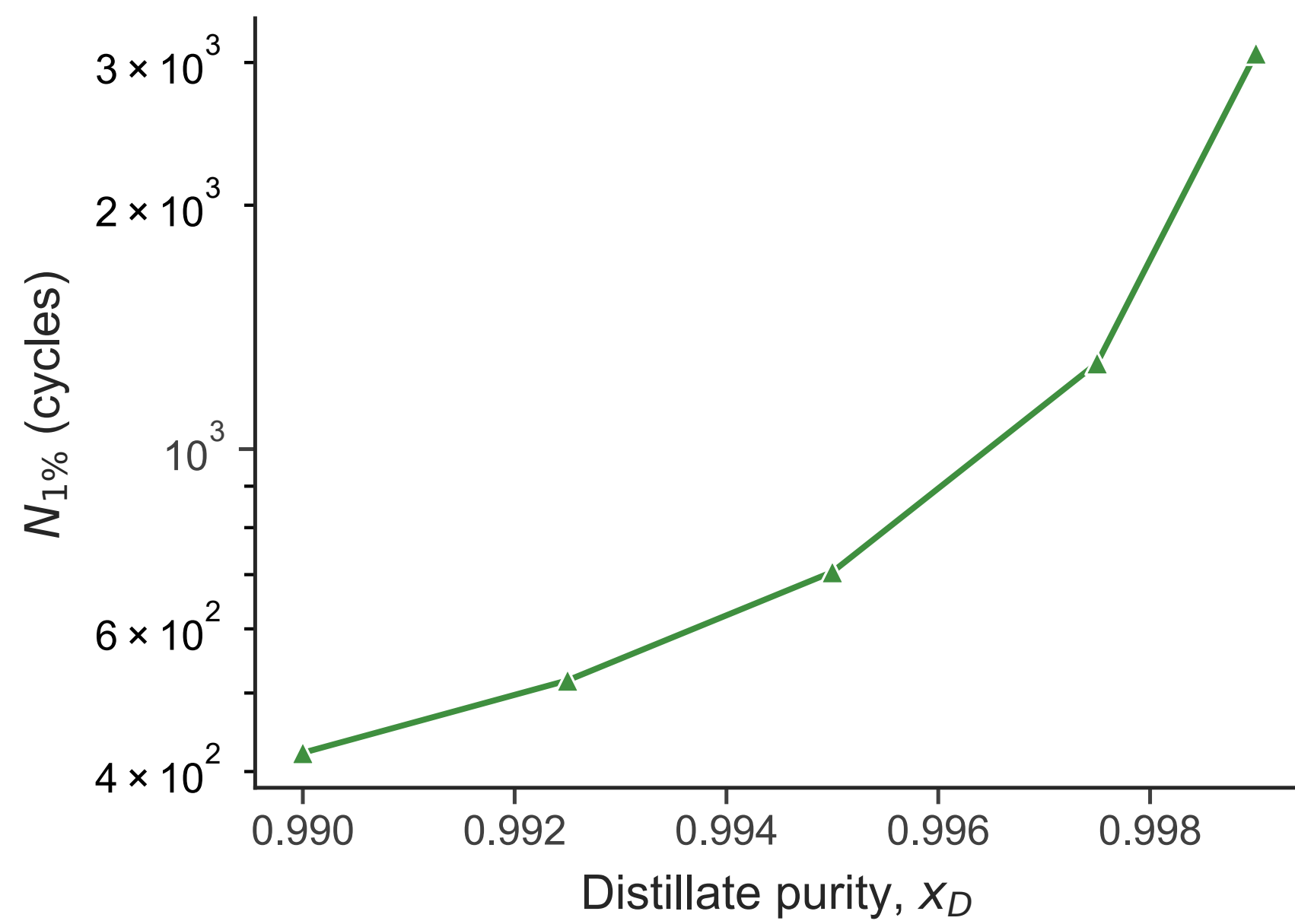
α	N	n_f	ρ	$N_{1\%}$ [cycles]	$t_{1\%}$ [h]
1.1	223	113	0.999954	100.683.69	419.52
1.2	117	60	0.999834	27.719.42	115.50
1.5	53	28	0.999204	5.781.94	24.09
2.0	31	17	0.997789	2.080.32	8.67
2.5	24	13	0.996425	1.286.03	5.36
3.0	20	11	0.995102	937.92	3.91
3.5	17	10	0.993492	705.33	2.94
4.0	16	9	0.992828	639.82	2.67
4.5	15	9	0.991493	539.03	2.25
5.0	14	8	0.991001	509.46	2.12

All ten states satisfy $\rho < 1$. The dominant multiplier is real and positive, so the slowest return is monotonic; however, the recovery time increases by more than two orders of magnitude as α approaches unity.

Local stability does not guarantee operationally fast recovery.

PURITY, DISTURBANCES & DESIGN

CASE 6 | PRODUCT PURITY



Tightening (x_D, x_B) from $(0.990, 0.010)$ to $(0.999, 0.001)$ changes

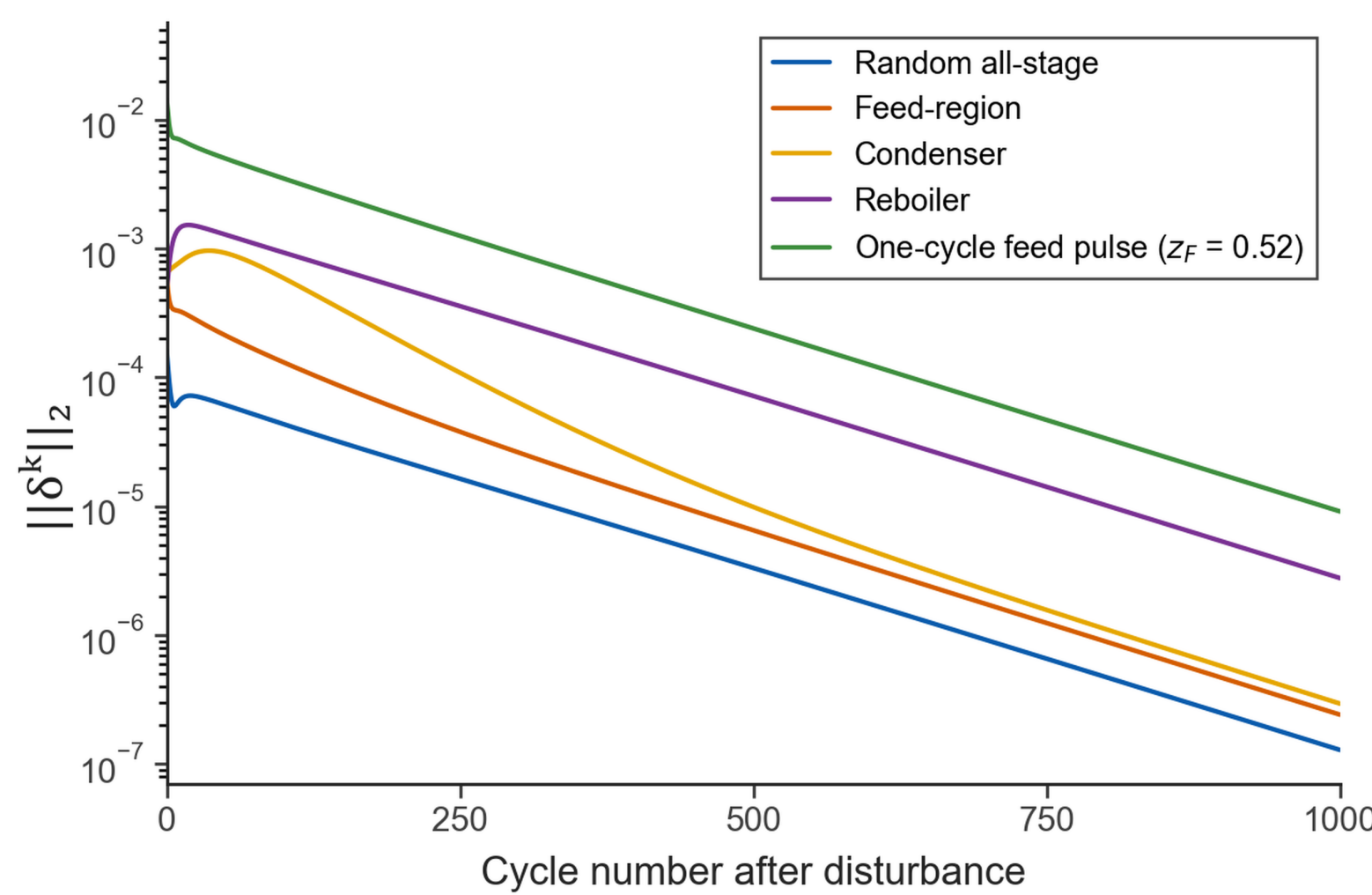
$$\rho : 0.98914 \rightarrow 0.99851, \quad t_{1\%} : 1.76 \rightarrow 12.83 \text{ h}.$$

The cycle-average vapor rate increases only from 0.02208 to 0.02279 kmol/s. High purity therefore carries a much larger recovery penalty than vapor penalty. The slow mode also spreads from the lower stripping section toward the rectifying section and column boundaries.

FIVE PURITY SPECIFICATIONS

x_D	.9900	.9925	.9950	.9975	.9990
$\bar{V}_{\text{cyc}}$	.02208	.02221	.02235	.02253	.02279
$t_{1\%}$ [h]	1.76	2.16	2.94	5.32	12.83

CASE 7 | NONLINEAR DISTURBANCE RECOVERY



Five tests were applied: normalized random all-stage, feed-region, condenser, reboiler, and a one-cycle feed pulse $x_F : 0.50 \rightarrow 0.52$. All return to the same periodic orbit. Condenser and reboiler perturbations show short-time amplification before asymptotic decay.

The maximum nonlinear–linear relative norm error is $< 1\%$; the largest is **0.82%** for the feed pulse. This validates the local map for the tested finite disturbances, not global stability.

FIVE DISTURBANCE TESTS

Test	Imposed magnitude	$\ \delta^{1000}\ _2$	Max. error
Random all-stage	10^{-4} (max stage)	1.29×10^{-7}	0.16%
Feed-region	5×10^{-4}	2.41×10^{-7}	0.097%
Condenser	5×10^{-4}	2.94×10^{-7}	0.28%
Reboiler	5×10^{-4}	2.77×10^{-6}	0.42%
Feed pulse	$\Delta x_F = 0.02$	9.12×10^{-6}	0.82%

DESIGN IMPLICATIONS

- Report cycle-average vapor requirement and recovery together.
- Use ρ for local classification, but use $N_{1\%}$ or $t_{1\%}$ to communicate operational recovery.
- The dominant eigenvector identifies the tray region supporting the slow mode; it does not by itself complete sensor or controller design.
- Compare $t_{1\%}$ with the allowable off-spec interval; if recovery is too slow, change the operating policy or develop closed-loop control.

Closed-loop extension. The local return map gives the state dynamics needed for a future feedback formulation:

$$\delta \mathbf{x}^{k+1} = (\mathbf{J}_x + \mathbf{B}_u \mathbf{K}) \delta \mathbf{x}^k.$$

The present study supplies $\mathbf{J}_x$; controller synthesis additionally needs $\mathbf{B}_u$, measurement timing, estimation, constraints, and actuator dynamics.

Transient growth. The ρ^k curve is an asymptotic reference, not a strict norm bound. Here $\kappa(V) \approx 2.7 \times 10^8$ and $\|\mathbf{J}_x\|_2 \approx 1.35 > 1$ although $\rho = 0.99349 < 1$; non-normality explains the short-time amplification.

CONCLUSIONS

- The finite-stage vapor-requirement reduction is **10.20–15.40%** at $N = \lceil 2N_{\min} \rceil$, but only **0.37–4.74%** at $N = \lceil 5N_{\min} \rceil$; changing t_V redistributes instantaneous vapor while changing $\bar{V}_{\text{cyc}}$ by $< 0.05\%$.
- All optimized periodic states examined are locally stable: every Floquet multiplier lies inside the unit circle.
- The base case is stable but weakly attracting: $\rho = 0.993492$, $N_{1\%} = 705.32$ cycles, and $t_{1\%} = 2.94$ h; the slow mode is concentrated near stage 15.
- Separation difficulty controls recovery: $\alpha = 1.1$ requires 419.52 h, while $(x_D, x_B) = (0.999, 0.001)$ requires 12.83 h. Vapor reduction and recovery speed must therefore be reported together.
- The local map predicts all five tested nonlinear recoveries with $< 1\%$ relative norm error. Feedback-control design remains future work.

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